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# AL-JUNAID INSTITUTE GROUP CS502 Grand Quiz

1.	The sequence of merge sort algorithm is:
	a. Divide Combine-Conquer
	b. Conquer-Divide-Combine
	c. Divide-Conquer-Combine Page 27
	d. Combine-Divide-Conquer
2.	·
	be put in the bag or not. Fractional items are not allowed.
	a. 0
	b. 1
	c. 0/1 Page 91
	d. Fractional
3.	In Selection algorithm, we assume pivot selection takes theta
	running time.
	a. n Page - 36
	b. n2
	c. n3
	d. log (n)
4.	
	maximum elements removed from top
	a. We call merge Sort Algorithm
	b. it becomes Order n2 Algorithm
	c. Divide and Conquer strategy helps us
	d. We are left with a hole Page – 41
5.	If matrix A of dimension p x q is multiply with matrix B of dimension
	q x r, then each entry in resultant matrix takes time.
	a. O (q) Page - 84
	b. O (1)

c. O (p x q)

d. O (q x r)



A	L-JUNAID INSTITUTE GROU
<del></del>	is a method of solving a problem in which we check all
	possible solutions to the problem to find the solution we need.
	a. Plane-Sweep Algorithm
	b. Sorting Algorithm
	c. Brute-Force Algorithm google
	d. Greedy approach
7.	The worst case running time of Quick sort algorithm
	a. Cannot be quadratic
	b. Is quadratic google QuickSort and its Analysis (codesdope.com) &
	http://personal.kent.edu/~rmuhamma/Algorithms/MyAlgorithms/Sorting/quickSort.htm
	c. Is always Exponential
	d. Is linear
8.	In max heap (for Heap Sort algorithm), when every time maximum
	element is removed from top we replace it with leaf in the tree.
	a. second last
	b. Last Page -41
	c. First
	d. Any
9.	Quick sort algorithm was developed by -
	a. AlferdAho
	b. Sedgewick
	c. John Vincent Atanasoff
	d. Tony Hoare – Google wikipedia
10	. If Matrix-A has dimensions "3x2" and Matrix-B has dimensions
	"2x3", then multiplication of Matrix-A and Matrix-B will result a
	new Matrix-C having dimensions.

http://www.calcul.com/show/calculator/matrix-multiplication

a. 3x2b. 2x3c. 2x2d. 3x3

11. For comparison-based sorting algorithms, it is possible to sort more efficiently than Omega n log(n) time.

a. Always

b. Not

c. Sometimes

P-54

d. Sometimes not
12. Dynamic Programming approach is usually useful in solving
optimization problems.
a. True
b. False
13. In Sorting the key value or attribute from an ordered domain.
a. Must be page 39
b. Not always
c. May be
d. Occasionally
14. Result of asymptotical analysis of n(n -3) and 4n*n is that
a. n(n-1) is asymptotically Less
b. n(n-1) is asymptotically Greater
c. Both are asymptotically Not equivalent
d. Both are asymptotically Equivalent page 23 (4n*n= 4n²)
15. Floor and ceiling are to calculate while analyzing
algorithms a. Very easy
b. Usually considered difficult P-31
c. 3rd Option is missing
d. 4th Option is missing
16 of reference is an important fact of current processor technology.
a. Defining b. Assigning
c. Formality
d. Locality P-8
17. In max-heap, largest element is stored at root node. Where is
the smallest element stored?
a. Right Node
b. Leaf Node
c. Middle Node
J

d. Left Node



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18. In average-case time analysis of Quick sort algorithm, the most balanced case for partition is when we divide the list of elements into			
a. Equal no. of pieces as of input elements			
b. Single piece exactly			
c. Two nearly equal pieces			
d. Three nearly equal pieces			
19. Which of the following is calculated with Big O notation?			
a. Medium bounds			
b. Upper bounds Page - 25			
c. Lower bounds			
d. Both upper and lower bounds			
20. Edit distance algorithm based onstrategy			
a. Greedy			
b. Dynamic Programming Page - 81			
c. Divide and Conquer			
d. Searching			
21. In Heapsort Algorithm, total time taken by heapify procedure is			
a. O (log n) Page-43			
b. O (log2 n)			
c. O (n log n)			
d. O (n2 log n)			
22. Al-Khwarizmi was a/an			
a. Artist			
b. Mathematician P-7			
c. Astronomer			
d. Khalifah			
23. When matrix A of 5x3is multiply with metric B of 3x4 then the			
number of multiplication required is: Not found exactly			
a. 15			

b. 12

c. 36

d. 60 Not Found exactly but as per formula at page 84,



24. Pseudo code of algorithms are to be read by	
a. People Page -12	
b. RAM	
c. Computer	
d. Compiler	
25. The sieve technique is a special case, where the number of sub-problems is J	ust
a. 1 P-34	
b. 2	
c. 3	
d. 4	
26. When a recursive algorithm revisits the same problem over and over	
again, we say that the optimization problem has sub-problems	<b>5</b> .
a. Overlapping - Google Search	
b. Over costing	
c. Optimized	
d. Three	
27. Sieve technique is very important special case of Divide-and-Conquer strategy	<b>/</b> .
a. True	
b. False	
28. In order to say anything meaningful about our algorithms, it will	
be important for us to settle on a	
a. Java Program	
b. C++ Program	
c. Pseudo program	
d. Mathematical model of computation P-10	
29. Merge sort is based on	
a. Brute-force	
b. Plan-sweep	
c. Axis-sweep	

d. Divide and Conquer

P-27



30. What time does Merge Sort algorithm take in order to sort an
array of 'n' numbers?
a. (n)
b. (log n)
c. (n^2)
d. (n log n) Google Search 31. In Heap Sort
31. algorithm, the first step is to
a. Call Build-Heap procedure Page - 46
b. Sort the array in descending order
c. Call Heapify procedure
d. Find the number of input elements
32. The definition of theta-notation relies on proving asymptotic bound.
a. One
b. Lower
c. Upper
d. Both lower & upper Page - 25
33. In merge sort algorithm, to merge two lists of size n/2 to a list of size n, takes
time.
a. Theta (n) Page - 32
b. Theta log(n)
c. Theta log2(n)
d. Theta n log(n)
34. We can make recursive calls in Fibonacci Sequence.
a. Infinite
b. Finite google
c. Only one
d. Zero
35. Following is NOT the application of Edit Distance problem.
a. Speech recognition

**b.** Spelling Correction

c. Ascending Sort

Page - 76

d. Computational Molecular Biology



36. In plane sweep approach, a vertical	-
plane and structure is used for hold	ding the maximal points lying
to the left of the sweep line.	
a. Array	
b. Queue	
c. Stack	Page - 18
d. Tree	
37. When a heapify procedure is applied	
heap, then at each level, the compar	ison performed takes time:
a. It will take (log n).	
b. It can not be predicted	
c. It will take O (1).	Page - 43
d. Time will vary according to th	e nature of input data.
38 time is the maximum running	time over all legal inputs.
a. Worst-case	Page - 13
b. Average-case	
c. Best-case	
d. Good-case	
39. Efficient algorithm requires less co	mputational
a. Memory	
b. Running Time	
c. Memory and Running Time	Page - 9
d. Energy	
40. For average-case time analysis of 0	Quick sort algorithm, Pivot
selection is on average basis from	
a. half of the input values	
b. all possible random values	Page - 50
c. Pivot is input separately	
d. values greater than 5	
41. Selection algorithm takes theta	

a. (n2)

b. (n) Page - 37

c. log(n)

d. n log(n)

42. Recurrence can be described in terms of a tree.		
a. Yes	Page - 31	
b. No		
43. Time complexity of Dynamic Program	nming based algorithm for	
computing the minimum cost of Chai	n Matrix Multiplication is	
a. Log n		
b. n		
c. n^2 (n square)		
d. n^3 (n cube)	Page -90	
44. The Iteration method is used for		
a. Comparing sorting algorithms		
b. Solving Recurrence relations	Page 31	
c. Merging elements in Merge s		
d. Dividing elements in Merge's		
45. In 3-Dimensional space, a point P l	nas coordinate(s).	
a. (X, Y)		
b. (X, 0)		
c. (0, Y)		
d. (X,Y, Z)	hand adding the second	
46. Chain matrix multiplication problem can		
a. Dynamic programming	Page - 85	
b. Greedy		
c. Divide and conquer		
d. Sorting 47. Merge sort have running timerunning	time of Hoan sort. Not found exactly	
a. Greater than	time of fleap soft. Not found exactly	
	Coords	
c. Equal to	<b>Google</b>	
d. Different than		
d. Dilielent tildli		

48. Median is not useful measure of central tendency of given input set especially when the distribution of values is highly skewed.

a. True



49. We do not need to mathematically prove that for comparison-
based sorting algorithms always takes Omega nlog (n) time.
a. True Google & VU Tech (pg 46 not very clear)
b. False
50. The Omega-notation allows us to state only the asymptoticbounds
a. Middle
b. Lower Page 25
c. Upper
d. Both lower & upper
51. Both lower & upperSorting can be in
a. Increasing order only
b. Decreasing order only
c. Both Increasing and Decreasing order GOOGLR Search
d. Random order
52. Radix sort performs sorting the numbers digit (s) at a time.
a. One Page - 71
b. Two
c. Three
d. All
53. Quicksort is a/an and sorting algorithm.
a. Not in place, not stable one
b. In place , not stable one Page - 54
c. In place , stable one
d Not in place, stable one
d. Not in place , stable one
54. Consider three matrices X,Y,Z of dimensions 1x2, 2x3,3x4
54. Consider three matrices X,Y,Z of dimensions 1x2, 2x3,3x4
54. Consider three matrices X,Y,Z of dimensions 1x2, 2x3,3x4 respectively. The number of multiplications of (XY) Z is:
54. Consider three matrices X,Y,Z of dimensions 1x2, 2x3,3x4 respectively. The number of multiplications of (XY) Z is:  a. 18  As per lecture slides
54. Consider three matrices X,Y,Z of dimensions 1x2, 2x3,3x4 respectively. The number of multiplications of (XY) Z is:  a. 18 As per lecture slides b. 32

55. In Fibonacci Sequence, unnecessary repetitions do not exist at all.

a. True

b. False Page – 74



56. It is not a Fibonacci sequence . 1,1,1,2,3,5,8,13,21,34,55,
a. True Page - 73
b. False
57. Heap sort is a/ an and sorting algorithem.
a. Not in place, not stable one
b. In place , not stable one Page - 54
c. In place , stable one
d. Not in place , stable one
58. Identify the True Statement
<ul> <li>a. The knapsack problem does not belong to the domain of optimization problems.</li> </ul>
b. The knapsack problem belongs to the domain of optimization
problems. Page - 91
c. The Knapsack problem cannot be solved by
using dynamic programming
d. The knapsack problem is optimally solved by using
brute force algorithm.
59. In Dynamic Programming, our approach is to
a. Develop the solution in a top-down fashion
b. Express the problem non-recursively
c. Build the solution in a bottom-up fashion Page - 75
d. Input several sub-problems simultaneously
60. Counting sort is suitable to sort the elements in range 1 to K;
a. K is large
b. K is small Page - 57
c. K may be large or small
d. None
61. We can multiply two matrices A and B only when they are
compatible which means
a. Number of columns in A must be equal to number of rows in B
it seems Correct as per page 84

b. Number of rows and columns do not matter



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	c. Number of columns in A must be	equal to number of columns in B
	d. Number of rows in A must be	equal to number of rows in B
62. Ma	atrix multiplication is a (n)	operation.
	a. Commutative	
	b. Associative	Page 85
	c. Neither commutative nor asso	ciative
	d. Commutative but not associat	ive
63. In	Dynamic Programming approach,	solution is modified / changed
	a. Always once	
	b. At each stage	oogle and wikipedia
	c. Only for specific problems	
	d. At 4 <sup>th</sup> stage only	
64. In	Knapsack problem, the goal is to put ite	ems in the Knapsack such that
the	e value of the items is subje	ect to weight limit of knapsack.
	a. Minimized	<b>Y Y</b>
	b. Decreased	
	c. Maximized	Page - 91
	d. None of the given options	
65. Ar	າ in-place sorting algorithm is one	that uses
ad	lditional array for storage.	
	a. Always	
	b. Permanently	
	c. Does not	Page - 54
	d. Sometime	
66. M	emoization is a part of Dynamic Pi	rogramming Strategy.
	a. True	Page - 74
	b. False	
	natrix A of dimension 2x4 is multiply wi	
th	e dimension of resultant matrix is	Not found exactly
	a. 2x4	

b. 4x3

c. 3x4

d. 2x3 It seems correct as per second last Para of page 84



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68. In Dynamic Programming approach, we do not store the solution
to each sub-problem in case if it reappears.
a. True
b. False Page - 75
69. Dynamic Programming is a problem-solving approach in which
a. Problem is solved in Zero time
b. Solution is developed only at final stage
c. Both are correct
d. Both are incorrect google
70. In Fibonacci sequence, each term is calculated by previous terms.
a. Subtracting, Two
b. Adding, Three
c. Adding, Two Page - 73
d. Multiplying, Two
71. Selection sort is not an in-place sorting algorithm.
a. True Page - 54
b. False
72. If there are $\theta$ (n <sup>2</sup> ) entries in edit distance matrix then the total running time is
a. θ (n)
b. θ (1)
c. θ (n <sup>2</sup> ) Page – 84
d. θ (n logn)
73. The only way to convert a string of i characters into the empty
string is with i deletions, represented as
a. E(0.j) =j
b. E(i.j) = 1
c. E(0.i) = j
d. E (i.0)=I Page - 78
74. Dynamic programming formulation of the matrix chain multiplication
problem will store the solutions of each sub problem in an

a. Array

b. Table Page - 86

c. Variable

d. class



75. We can use the optimal substructure property to devise a
formulation of the edit distance problem.
a. Selective
b. Optimum
c. Iterative
d. Recursive Page - 78
76. Sorting is performed on the basis of
a. Computational resources
b. Asymptotic notation
c. Summation
d. Some key value of attribute page- 39
77. In Heap Sort algorithm, we call Build-heap procedure
a. Only once page 46
b. Twice
c. Thrice
d. As many times as we need
78. Radix sort is not a non-comparative integer sorting algorithm.
a. True Google Search
b. False
79. In the statement "output P[1].x, P[1].y", the number of times
elements of P are accessed is
a. 1
b. 2 page 14
c. 3
d. 4
80. The main purpose of mathematical analysis is measuring the
required by the algorithm.
a. Space
b. Execution time P-13
c. Inputs & outputs

d. Execution time and memory



81.	provides us more accurate result when input values a					
	not closer with each other					
	a. Average					
	b. Median P-34					
	c. Mode					
	d. Mean					
82.	The process of ends when you are left with such tiny					
	pieces remaining that it is trivial to solve them.					
	a. Brute-force					
	b. Plan-sweep					
	c. Divide and Conquer P-27					
	d. Axis-sweep					
83.	overcomes the limitations of by					
	working as per positional notations of numbers.					
	a. Counting sort, Radix sort					
	b. Radix sort, Counting sort P-71					
84. Memorization is a part of Dynamic Programming strategy.						
	a. True P-74					
	b. False					
85.	Rank of an element can be defined as					
	a. One minus the number of elements that are smaller					
b. Two plus the number of elements that are greater						
	c. One plus the number of elements that are smaller P-34					
	d. Two minus the number of elements that are smaller					
86.	If the time complexity of an algorithm is given by O (1),					
	then its time complexity would be					
	a. Polynomial					
	b. Exponential					
	c. Constant - Wikipedia					
	d. Average					

87. Quick sort is a recursive algorithm.

a. True Wikipedia ; Google



88. The asymptotic growth of n(n+1)/2 is:					
<ul> <li>a. O(n<sup>2</sup>) As the n<sup>2</sup> term has the largest contribution, the Big-O complexity is O(n<sup>2</sup>)</li> <li>b. O(n)</li> </ul>					
c. O(n+2)					
d. O(n log n)					
89. Approach of solving geometric problems by sweeping a line					
across the plane is called sweep.					
a. Line					
b. Plane Page 18					
c. Cube					
d. Box					
90. As per algorithm of Dynamic Programing, we need to store					
a. First sub-problem only					
b. Best solution only					
c. Intermediate sub-problems Pg:75					
d. Final solution only					
91. In Sieve technique, we solve the problem					
a. In recursive manner Pg:34					
b. Non recursively					
c. Using Merge Sort algorithm					
d. Using Brute force technique					
92. One of the limitation in 0/1 knapsack is that an item can either be					
in the bag or not.					
a. Use					
b. Put Pg:91					
c. Move					
d. Store					
93. Which one is not passed as parameter in Quick sort algorithm?					
a. End of the array					
b. Middle of the array					

c. Array (containing input elements)

Google

d. Start of the array



94. In the analysis of Selection algorithm, we get the convergent				
a. Harmonic				
b. Linear				
c. Arithmetic				
d. Geometric Pg:37				
95. A Random Access Machine (RAM)is an idealized machine				
withrandom access memory.				
a. Infinite large Pg:10				
b. 512 MB				
c. 256 MB				
d. 2 GBs				
96. While analyzing Selection algorithm, we make a number of				
passes, in fact it could be as many as				
a. n(n+1)				
b. log(n) Pg:37				
c. n/3				
d. n/4				
97. In Random Access Machine (RAM), instructions are executed in				
a. Parallel				
b. Batch				
c. One by One Pg:10				
d. Multiple times				
98. In selection problem, the rank of an element will be its position				
a. First				
b. final Pg:34				
c. Second last				
d. Last				
99. The worst-case running time of Merge sort is in order to				
sort an array of n elements.				
a. O(log n)				

b. O(n)

c. O(n log n) page 40 and google

d. O(n)



	100. f(n) and g(n) are asymptotically equivalent. This means				
tł	that they have essentially the same	<u>_</u> .			
	a. Results				
	b. Variables				
	c. Size				
	d. Growth rates	:23			
101.	. An algorithm is a mathematical entity. Which i	s independent of			
	a. Programming language				
	b. Machine and Programming language				
	c. Compiler and Programming languag	le			
	d. Programming language Compiler an	d Machine P:07			
102.	2. In Quick sort algorithm, Pivots form				
	a. Stack				
	b. Queue				
	c. Binary Search Tree	P:49			
	d. Graph				
103.		s within range 1 to P. where			
	a. P is large				
	b. P is small	P-57			
	c. P is very large				
	d. P is undetermined				
	I. In asymptotical analysis of n'(5 2)-3, as	_			
tł	the dominant (fastest growing) term is some constant times				
	a. n_1				
	b. n				
	c. n+1				
	d. n*n P-23				
105.					
	knapsack. a. Lighter	_			
	b. Fractional P	<mark>-91</mark>			

c. Whole

d. Weighty



106. Fibonacci Sequence was named on, a famous
mathematician in 12th Century.
a. Fred Brooks
b. Grady Booch
c. Leonardo Pisano P-73
d. Edgar F. Codd
107. In Heap Sort algorithm, we build for ascending sort.
a. Max heap P-41
b. Min heap
108. Bubble sort is not an in-place sorting algorithm.
a. True
b. False
109. In partition algorithm, the subarray has elements
which are greater than pivot element x.
a. A[pr]
b. A[pq-1]
c. A[q]
d. A[q+1r] P-46
110. In Heap Sort algorithm, if heap property is violated
a. We call Build heap procedure P-43
b. We call Heapify procedure
c. We ignore
d. Heap property can never be violated
111 is not a characteristic of Random Access Machine.
a. Single-Processor P-10
b. Assigning a value to a variable
c. Locality of reference
d. Executing an arithmetic instruction
112. The only way to convert an empty string into a sting of j
characters is by doing j insertions, represented as

a. E(i,j) = 1

b. E(1,0) = 1

c. E(0,j) = j page 78

d. E(1,j)=j



113. In Selection problem, the Sieve technique works in
a. Non-recursive manner
b. Constant time
c. Phases page 34
d. One complete go
114. Algorithm is a sequence of computational steps that
the input into output.
a. Merge
b. Assign
c. Transform page 7
d. Integrate
115. If pj dominates pi and pi dominates ph then pj also dominates
ph, it means dominance relation is
a. Transitive page 18
b. Non Transitive
c. Equation
d. Symbolic
116. To find maximal points in brute-force algorithm each point of
the space is compared against of that space.
a. One other point
b. All other points page 11
c. Few other points
d. Most of the other points
117. In the following code the statement "cout< <j;"executes< td=""></j;"executes<>
times. for (j=1; j<=5; j = j+2)
cout< <j;< td=""></j;<>
a. 5 times
b. 2 times
c. <mark>3 times</mark>

d. 0 times



118. In merge sort algorithm, we split the array around the
index q. a. Entring
b. Mid page 17
c. Exiting
d. Summing
119. In Selection problem, the Sieve technique
a. Add some more input items each time
b. Do not work recursively
c. Do not uses Divide and Conquer approach
d. Eliminates undesired data items each time
120. Consider three matrices X, Y, Z of dimensions 1 x 2, 2 x 3,
3 x 4 respectively. The number of multiplications of X(YZ) is .
a. 16
b. 32
c. 26
d. 32 page 84
121. In Heap Sort algorithm, the total running time for Heapify procedure is
a. Theta (log n)
b. Order (log n)
c. Omega (log n)
d. O(1) i.e. Constant time
122. The sieve technique works where we have to find
items(s) from a large input.
a. Single page 34
b. Two
c. Three
d. Similar
123. In Dynamic Programming based solution of Knapsack Problem,
if we decide to take an object i , then we gain
· · · · · · · · · · · · · · · · · · ·



- a. W(Total Weight of Knapsack)
- b. V (Total Value of all items)
- c. vi (Value of object i) page 93
- d. Nome of the given option



	<u> </u>
124.	While Sorting, the order domain means for any two input elements x and y satisfies only.
_	a. x < y page 39
	b. x > y
	c. x = y
	d. All of the above
125	For solving Selection problem, we introduced Sieve technique due to
120.	Tor solving defection problem, we introduced dieve technique due to
_	a. Using Decrease and Conquer strategy page 34
	b. Avoiding to sort all input data
	c. Eliminating Rank of an element
	d. Using Brute-force approach
126.	
_	oounds exist on how fast we can sort.
~	a. Searching
	b. Sorting page 38
	c. Both Searching & sorting
	d. Growing
127	In plane sweep approach, a vertical line is swept across
	he 2d-plane from
<u>.</u>	a. Right to Left
	b. Left to Right page 18
	c. Top to Bottom
	d. Bottom to top
<mark>128.</mark>	In generating Fibonacci sequence, we can avoid unnecessary repetitions by
	process.
	a. Tokenization
	b. Memorization page 43
	c. Randomization
	d. Memorization
129.	For values of n, any algorithm is fast enough.

a. Small page 14

- b. Medium
- c. Large
- d. Infinity



130.	Dynamic programming comprises of
	a. Recursion only
	b. Repetition only
	c. Recursion with Repetition
	d. No Repetition but Recursion page 75
131.	The function f(n)=n(logn+1)/2 is asymptotically equalient t nlog n :Here Lower
В	ound means function f(n) grows asymptotically at as fast as nlog n.
	a. Least page 23
	b. Normal
	c. Most
	d. At
132.	Counting sort has time complexity.
	a. O(n+k)
	b. O(n) page 58
	c. O(k)
	d. O(nlogn)
133.	Due to left complete nature of binary tree, the heap can be stored in
	a. Array page 40
	b. Structures
	c. Link List
	d. Stack
134.	Single item from a larger set of
	a. Constant
	b. Pointers
	c. Phases
	d. n items page 34
135.	In the clique cover problem, for two vertices to be in the same
g	roup, they must be each other.
	a. Apart from
	b. Far from

c. Near to

d. Adjacent to page 76



136.	How much time merge sort takes for an array of numbers?  a. T(n^2)  b. T(n)  c. T(log n)		
40-	d. T(n log n) page 40		
137.	In in-place sorting algorithm is one that uses arrays for storage.		
	a. No additional array page 54		
	b. An additional array		
	c. Both of above may be true according to algorithm		
<b>138.</b>	d. More than 3 arrays of one dimension		
	Brute-force algorithm for 2D-Maxima is operated by comparing		
þ	airs of points.  a. Two		
	b. Some		
	c. Most		
	d. All page 18		
120			
139. While Sorting, the ordered domain means for any two input elements x and y satisfies only.			
C	a. x > y		
	b. x < y		
	c. x=y		
	d. All of the above page 38		
140	Quick sort is.		
140.	a. Stable & in place		
	b. Not stable but in place page 54		
4	c. Stable but not in place		
	d. Some time stable & some times in place		
141.	Which may be a stable sort?		
	a. Merger		
	b. Insertion		

c. Both above page 54

d. None of the above



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142. For the Sieve Technique we take time.
a. T(nk) page 34
b. IT(n / 3)
c. n^2
d. n/3
143. Continuation sort is suitable to sort the elements in range 1 to k.
a. K is Large
b. K is not known
c. K may be small or large
d. K is small page 54
144. Asymptotic growth rate of the function is taken over
case running time
a. Best
b. Worst page 14
c. Average
d. Normal
145. The sieve technique is a special case, where the number of
sub problems is just.
a. 5
b. Many
c. 1 page 34
d. Few
146. In Quick sort, we don't have the control over the sizes of recursive calls.
a. True page 49
b. False
c. Less information to decide
d. Ether true or false
147. Before sweeping a vertical line in plane sweep approach, in start sorting
of the points is done in increasing order of their coordinates
a. X page 18

b. Y

c. Z

d. X , Y



	<u>E GOTTAID INSTITUTE GROOT</u>
148.	Random access machine or RAM is a/an.
	a. Machine build by Al-Khwarizmi
	b. Mechanical machine
	c. Mathematical model page 10
	d. Electronics machine
149.	The Huffman codes provide a method of encoding data
	nefficiently when coded using ASCII standard.
	a. True
	b. False page 99
150.	A heap is a left-complete binary tree that confirms to the
	a. increasing order only
	b. decreasing order only
	c. heap order page 40
	d. log n order
151.	If we associate (x, y) integers pair to cars where x is the speed of the car and
у	is the negation of the price. High y value for a car means a car.
	a. Fast
	b. Slow
	c. Expensive
	d. Cheap
152.	Which one of the following sorting algorithms is the fastest?
	a. Merge sort
	b. Quick sort
	c. Insertion sort
	d. Heap sort
153.	Quick sort algorithm divide the entire array into sub arrays.
	a. 2
	b. 3
	c. 4
	d. 5
154.	In brute force algorithm, we measure running time T(n) based on

a. Average-case time and best-case time

b. Worst-case time and average-case time page 46

c. Worst-case time and best-case time

d. Best-case time and staring-case time



155.	For 2D Maxima problem. Plane Sweep algorithm first of all			
	a. Sorts all points			
	b. Delete some points			
	c. Output the elements			
	d. Pushes all points on stack			
156.	There are entries in the Edit Distance Matrix			
	a. e (n)			
	b. e (n₂) page 84			
	с. ө (n+2)			
	d. e (n + 100)			
157.	Which symbol is used for Omega notation?			
	a. (O)			
	b. (e)			
	<b>c.</b> (Ω)			
	d. (@)			
158.	Selection sort is asorting algorithm			
	a. In-place page 54			
	b. Not In-Place			
	c. Stable			
	d. in-partition			
	In Dynamic Programming based solution of knapsack problem,			
to	compute entries of 'V', we will imply a(n) approach.			
	a. Subjective			
	b. Inductive			
	c. Brute Force			
	d. Combination			
160.	We do not need to prove comparison-based sorting			
algorithms by mathematically. It always takes time.				
	a. Big Oh nlog(n)			
	b. Omega nlog(n) NOT SURE			

- c. Omega n(n^2)
- d. Theta nlog(n)



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161.	1. Merge sort is a/an and s	orting algorithm
	a. Not in-place, not stable one	
	b. In-place, not stable one	
	c. In-place, stable one	
	d. Not in-place, stable one page 5	4
162.	2. Cubic function will a quadratic fu	unction.
	a. Prove	<b>A</b>
	b. be equal to	
	c. overtake Page 25	
	d. find	
163.	<ol><li>Insertion sort is a sorting algorithm</li></ol>	ithm
	a. Unstable	
	b. In-place Page 54	
	c. Not In-Place	
	d. in-partition	7
164.	4. To check whether a function grows faster or s	slower than the other
fı	function, we use some asymptotic notations, wh	nich is
	a. Big-oh notation	
	b. Theta notation	
	c. Omega notation	
	d. All of the given	
165.	5. Asymptotic growth of 8n^2 + 2n – 3 is:	
	a. Θ(n^2 + n)	
	b. Θ (n^2) page 14	
4	c. Θ(8n^2)	
	d. Θ(8n^2 + 2n)	
166.	6. In the analysis of algorithms, pla	ys an important role.
	a. text analysis	
	<mark>b. time</mark>	
	c. growth rate	

d. money



167.	In inductive approach of knapsack problem, we consider 2 cases,
0	or
	a. Median, Mode
	b. Recursive, Iterative
	c. Leave object, Take object page 93
	d. Sequentially. Parallel
168.	Random Access Machine (RAM) can executeinstructions
	a. only logical
	b. parallel
	c. only arithmetic
	d. logical and arithmetic
169.	
	a. Greedy
	b. Merge sort
	c. Processing as there is no algorithm by this name
	d. Brute Force
170.	Bubble sort takes theta in the worst case
	a. (n2) page 39
	b. (n)
	c. log(n)
4-4	d. nlog(n)
	If matrix A of dimension p × q is multiply with matrix B of
a	imension q × r, then dimension of resultant matrix is:
	a. p × q
	b. p × r page 84 c. q × r
470	d. r×p
1/2.	Dynamic Programing algorithms often use some kind of
_	to store the results of intermediate sub-problems
	a. table (Page 75)

- b. variable
- c. stack
- d. loop



# AL-JUNAID INSTITUTE GROUP 173. is in place and it.

175.	is in-place softing algorithm.
	a. Bubble sort (Page 54)
	b. Merge sort
	c. Linear search
	d. Binary Search
174.	Which one of the following problems can be solved using dynamic problem?
	a. Bubble sort problem
	b. Matrix chain multiplication problem page 85
	c. Greedy search problem
	d. Fractional knapsack problem
175.	In chain matrix multiplication, solutions of the sub-problems are stored in a
_	·
	a. Array
	b. Table page 86
	c. Tree
	d. Link list
176.	What is the average running time of a quick sort algorithm?
	a. O(n^2)
	b. O(n)
	c. O(n log n) (Page 49)
	d. O(log n)
177.	Sorting Algorithms having O running time are
C	onsidered to be slow ones.
	a. (n)
4	b. (n^2) (Page 39)
	c. (nlog(n))
	d. (log(n))
178.	While solving Selection problem, in Sieve technique we partition input data
_	
	a. In increasing order



- b. In decreasing order
- c. According to Pivot
- d. Randomly



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179.	is the process of avoiding unnecessary repetitions
by	y writing down the results of recursive calls and looking them
u	p again if we need them later.
	a. Loop
	b. Memoization page 74
	c. Recursion
	d. Function
180.	In average-case time the probability of seeing input is denoted by
	a. p{I}
	b. p[l]
	c. p <i></i>
	d. p(i) page 13
181.	While applying the Sieve technique to selection sort, how to
cł	hoose a pivot element.
	a. Through mean
	b. Linear
	c. Randomly page 35
	d. Sequentially
	Number of of the pseudo code are counted to measure
th	ne running time.
	a. Inputs
	b. Outputs
	c. Steps page 13
	d. Pages
183.	Developing a dynamic programming algorithm generally involves
Se	eparate steps.
	a. One
	b. Two page 75
	c. Three
404	d. Four
184.	8n^2+2n+3 will exceed c28(n), no matter how large we make
	a. n

b. 2n

c. c2 page 25

d. this quadratic equation



185.	The running time of quick sort algorithm
	a. Is impossible to compute
	b. Has nothing to do with pivot selection
	c. Is Random upon each execution
	d. Greatly influenced by the selection of pivot page 49
186.	involves breaking up the problem into sub problems
W	hose solutions can be combined to solve the global problem.
	a. Complexity Theory
	b. Dynamic programming solution
	c. Divide and Conquer Strategy page 34
	d. Greedy Algorithms
187.	In we have to find rank of an element from given input.
	a. Merge sort algorithm
	b. Selection problem page 34
	c. Brute force technique
	d. Plane Sweep algorithm
188.	How many steps are involved to design the dynamic programming strategy?
	a. 2
	b. 3
	c. 1
	d. 4 page 92
189.	In Bucket sort, if there are duplicates then each bin can be
	replaced by a a. Stack
	b. Linked list page 69
	c. Hash table
	d. Heap
190.	In merge sort algorithm, we split the array to find index q.
	a. from start
	b. midway page 28
	c. from end

d. both from start or end



191.	Find the	maximum	value of	f the ite	ms wl	nich (	can	carry
us	sing knap	osack Knap	osack we	eight ca	pacity	y = 50	).	

Item Weight Value

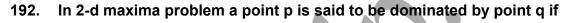
11070

22020

33080

470 200

- a. 280
- b. 100
- c. 90
- d. 200



- a.  $p.x \leq q.x$
- b. p.x <= q.x and p.y <= q.y page 17
- c. p.y <= q.y
- d.  $p.x \ge q.x$  and  $p.y \ge q.y$
- 193. Sorting can be in \_\_\_\_\_.
  - a. Increasing order only
  - b. Decreasing order only
  - c. Both increasing and decreasing order
  - d. Random order

- a. Array
- b. Linear
- c. Tree page 31
- d. Graph

- a. n
- b. n(log n)

c. n\*n page 18 d. n3



196.	In plane sweep approach of solving geometric problems, a
_	is swept across the plane.
	a. Line page 18
	b. Plane c. Cube
407	d. Box
197.	Which of the following is calculated with Big Omega notation?
	a. Medium bounds
	b. Upper bounds
	c. Lower bounds Page - 25
198.	d. Both upper and lower bounds
190.	is always based on divide and conquer strategy.  a. Bubble sort
	b. Selection sort
	c. Pigeon sort d. Quick sort page 46
100	d. Quick sort page 46  If a matrix has three rows and two columns, then dimensions
	f matrix will be:
U	a. 3x2
	b. 2x3
	c. 3x3
	d. 2x2
200.	
	a. Length
	b. running time google
4	c. size
	d. compile time
201.	Catalan numbers are related the number of different on 'n' nodes.
	a. Arrays
	b. linked lists

c. binary trees page 85

d. functions



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202.	Applying the sieve technique to selection problem,
е	lement is picked from array.
	a. Output
	b. Total
	c. Input
	d. Pivot page 35
203.	Dynamic Programming approach is usually useful in solving
р	roblems.
	a. Normal
	b. Optimization google
	c. Array
	d. Loop
204.	In recursive formulation of knapsack
	Problem: V [0, j] = for j>=0
	a1
	b. 0 page 93
	c. 1
	d. 2
205.	is a linear time sorting algorithm.
	a. Merge sort
	b. Radix sort page 71
	c. Quick sort
	d. Bubble sort
206.	Quick sort is one of the sorting algorithm.
	a. Fastest page 19
	b. Slowest
	c. Major
	d. Average
207.	The time assumed for each basic operation to execute on
R	AM model of computation is

- a. Infinite
- b. Continuous

c. Constant page 10

d. Variable



208. In Sieve Technique, we know the item of interest. a. True
b. False page 34
209. While analyzing algorithms, and usually considered difficult to calculate.
a. Finite, Infinite
b. Floor, ceiling google
c. Row, Column
d. Graph, Tree
210. While analysis of the brute-force maxima algorithm, an array
sorted in the reverse order is the type of case input.
a. Best
b. Worst page 14
c. Somewhat bad
d. Average
211 is not useful measure of central tendency of given
input set especially when the distribution of values is highly skewed.
a. Mean
b. Mode
c. Average
d. Median page 34
212. In asymptotical analysis of n(n-3) and 4n*n, as n becomes large,
the dominant (fastest growing) term is some constant times
a, n+1
b. n-1
c. n
d. n*n page 23
213. In addition to passing in the array itself to Merge Sort
algorithm, we will pass in other arguments which are indices.

a. Two

P-38

b. Three

c. Four

d. Five



# AL-JUNAID INSTITUTE GROUP 214. In 2d-maximal problem, a point is said to be if it is not

dominated by any other point in that space
dominated by any other point in that space.  a. Member
b. Minimal
c. Maximal P-11
d. Joint
215. Counting sort assumes that the numbers to be sorted are in the range
- K to n vulnama m in lamma
a. K to n where n is large
b. 1 to k where k is small (P-57)
c. K to n where k is small
d. k to n where n is small
216. Insertion sort is an efficient algorithm for sorting a
number of elements
a. Large
b. Small
c. Extra large
d. Medium
217. If the indices passed to merge sort algorithm are
then this means that there is only one element to sort.
a. Small page 28
b. Large
c. Equal
d. Not Equal
218. In Knapsack Problem, each item must be entirely accepted
or rejected, is called problem.
a. Fractional
b. 0-1 P-92
c. Linear
d. Optimal

219.		an algorithm is O(n). then it is called
	time complexity.  a. Linear	Wikipedia
	b. Constant	
	c. Average	
	d. Exponential	
220	•	analysis does not depend upon on
	ne distribution of input.	_ analysis asso not aspona apon su
•-	a. Merge sort	
	b. Quick sort	P-50
	c. Insertion sort	
	d. Heap sort	
221	We can use the	Property to devise a recursive
	ormulation of the edit dis	
	a. Small substructure	
	b. Algorithmic	_ ( ) / /
	c. Real	
	d. Optimal substructure	page 78
222.	The following sequence	
	1,2,3,5,8,13,21,34,55,	9 541154
	a. Optimize sequence	
	b. Fibonacci sequence	page 73
	c. Optimal sequence	page 13
	d. Overlapping sequence	26
223		ithm is best suited to sort an array
	f 2 million elements?	itilii is best suited to soft all array
. 0	a. Bubble sort	
	b. Insert sort	
	c. Merge sort	
	d. Quick sort	
	u. Quick suit	

e. Ridx Sort page 71



224.	We can improve the performance of quick sort if we could
b	e able to _,
	a. Skip input elements somehow
	b. Select two or more pivots page 34
	c. Skip any sub-array completely
	d. Eliminate recursive calls
225.	The problem with the brute-force algorithm is that is uses in pruning out de
	a. Worst-case time
	b. No intelligence page 18
	c. Outside looping
	d. Artificial intelligence
226.	In chain matrix multiplication, the order of the matrices
	a. Can be changed
	b. Can not be changed page 85
	c. is equal
	d. is reverse
227.	In quick sort algorithm, we choose pivot
	a. Always the smallest element
	b. Greater than 5
	c. Randomly page 35
	d. Less than 5
228.	In Heap Sort algorithm. Heapify procedure is in nature.
	a. Recursive
	b. Non-Recursive page 43
	c. Fast
	d. Slow
229.	When matrix A of 5x 3 is multiplied with matrix B of 3 x 4 then
	ne number of multiplications required will be
	a. 15

b. 12

c. 36

<mark>d. 60</mark>



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230. An algorithm is said to be correct if for every instance,
it halts with the correct
a. Input, Output page 13
b. Design, Analysis
c. Value, Key
d. Key, Analysis
231. In chain matrix multiplication, table is filled
to find the multiplication of matrix.
a. row wise
b. column wise
c. diagonally
d. bottom-to-up page 86
232. If we have an equation 8n2+7f*n + 5f + 6 then is large, tern
will be muchxxxxxxxthe n term and will dominate the running time.
a. f g (n)
b. g (n) * 2
c. n * 2 page 23
d. f (n)
233. For quick sort algorithm. Partitioning takes theta
a. (n)
b. log(n)
c. n log (n)
d. n2log (n)
234. In Heap Sort algorithm, the maximum levels an element can move upward is
a. Theta (log n) page 43
b. Big-ch (log n)
c. Omega (log n)
d. 0 (1) i.e. Constant time

235. \_\_\_\_\_ programming is essentially recursion without repetition.

a. Fast

b. Dynamic page 75

c. Array

d. n (log n)

236.	There are no hard formal rules to the syntax of the	code.
	a. Basic	
	b. Programming	
	c. Pseudo	
	d. Assembly	
237.	In Heap Sort algorithm, to remove the maximum element even	ery time.
	a. We call Build-Heap procedure	
	b. Heap Sort algorithm terminates without result	
	c. We call heapify procedure	
	d. Nothing happens	
238.	Which process is used for avoiding unnecessary repetit	ions
а	nd looking them up again if we need them later.	
	a. Greedy Approach	
	b. Memoization page 74	
	c. Divide and conquer	
	d. Recursion	
239.	The worst-case running time of Quick sort is	in
0	order to sort an array of n element.	
	a. O(n log n) page 49	
	b. O(n)	
	c. O(n <sup>2</sup> )	
	d. O(log n)	
240.	Boolean operation is a operation on an ideali	zed
R	RAM model of computation.	
	a. Starting	
	b. Basic page 10	
	c. Advance	
	d. Normal	

- 241. In chain matrix multiplication, if there are n items, there are \_\_\_\_\_ ways in which outer most pair of parentheses can placed.
  - a. n^2
  - b. 2n
  - c. n+1
  - d. n-1 page 85
- 242. The number of nodes in a complete binary tree of height h is: a. 2 \* (h+1) 1
  - b. 2^(h+1) 1 page 40
  - c. 2 \* (h+1)
  - d. ((h+1)^2) 1